## FA-3300 <br> Heavy Duty Electric Actuator

## Introduction

The FA-3300 series synchronous motor-driven, reversible, heavy duty actuators are available for 3-point (floating) or with electric positioner for $0 . . .10 \mathrm{~V}$ or $0 . . .20 \mathrm{~mA}$ control. They feature factory calibrated pressure switches to provide specified close-off ratings.
These actuators are available with 6000 N nominal force and can be used in combination with VG8000 and VBD series valves in accordance with the maximum close-off pressure ratings specified.

Factory fitted options, such as $2 k \Omega$ feedback potentiometer and auxiliary switches are available. A hand wheel for manual positioning of the valve is standard on all models.


FA-3300 Actuator with VG8000 valve

## Features and Benefits

- Uses synchronous motor with calibrated pressure limit switches.
- Special clamp coupler.
- Models for 3-point and proportional 0... 10 V or $0 . . .20 \mathrm{~mA}$ control.
- Positioner with adjustable starting point, span, and direct / reverse action.
- Active $0 . . .10 \mathrm{~V}$ position feedback on proportional models.
- Optional auxiliary switches and feedback potentiometer available.
- A hand wheel is standard on all models.

Constant running time.
Fixed close-off force.
Provides easy mounting of the actuator on valves with slotted stem.
Allows optimum choice of electrical signal.

Provides flexibility in application. Allows easy sequencing from only one controller output signal.

Provides active signal for independent monitoring of position.

Provides potential free contacts for independent monitoring of the actuator's position.

Allows manual positioning independent from power supply.

## Ordering data

FA-

*) For other supply voltage and frequency, please contact your Johnson Controls supplier.

## Ordering Procedure

The valves and actuators can be ordered as separate units or a factory fitted combination. Should such a combination be required, please add " $+\mathbf{M}$ " after the order code for the actuator.

## For example:

For a 2-way valve, DN 65, kvs 63, PN16 plus actuator with electric positioner $0 . . .10 \mathrm{~V}$ input, $24 \mathrm{~V} / 50 \mathrm{~Hz}$ supply, order:

```
Item 1 VG82G1S1N
Item 2 FA-3341-7416
```

Alternatively, to order a factory fitted combination:

Item 1 VG82G1S1N
Item 2 FA-3341-7416+M

```
(valve body)
(actuator)
```

Accessory Kits for in-situ installation:

| EQ-1003-7101 | Two Auxiliary Switches and <br> Feedback Potentiometer $2 \mathrm{k} \Omega$ |
| :--- | :--- |
| EQ-1013-7101 | Feedback Potentiometer 135 $\Omega$ |

## Repair parts:

| EQ-1015-7101 | Electric Positioner 0...10 V or <br>  <br>  <br> $0 . . .20 \mathrm{~mA}$ plug-in module for in- <br> situ replacement. |
| :--- | :--- |

## Actuator-Valve combinations

The FA-3300 series heavy duty electric actuators are specifically designed to be used with the VG8000 and the VBD valve series. The ordering data for these valve bodies are as follows:

- VG8000 series (PN16 flanged valves)

| VG82-S1N | 2-way PDTC (NO) | DN 100... 150 |
| :---: | :---: | :---: |
| VG88]S1N | 3-way mixing | DN 100... 150 |
| VG89]LS1N | 3 -way diverting | DN 100... 150 |
| - VBD series | (PN25 flanged val |  |

VBD- 12-520 2-way PDTC (NO) DN 80... 150
VBD-T 18-520 3-way mixing DN $80 . . .150$

Please refer to the product bulletins "VG8000 Series Flanged Valves" and "VBD Series Flanged valves" for complete ordering information.

## Operation

## 3-point models

| Connections | Actuator Stem |
| :---: | :---: |
| $1-2$ | extends |
| $1-3$ | retracts |

## Proportional models

| Action <br> Jumper | Input control <br> signal | Actuator <br> Stem |
| :---: | :---: | :---: |
| Direct acting | increases | retracts |
|  | decreases | extends |
| Reverse | increases | extends |
| acting | decreases | retracts |

## Mounting instructions

When mounting the actuator on a valve, please follow the instructions below:

- It is recommended that the valves be mounted in the upright position, in an easily accessible location. When mounted horizontally, the yoke should be fitted such that the stanchions are positioned vertically one above the other.

- The actuator must be protected against dripping water, which could enter the housing and damage the mechanism or motor.
- Do not cover with insulating material.
- Sufficient clearance must be allowed for actuator removal (refer to the dimension drawings).
- The valve must be installed so that the plug seats against the flow as indicated by the arrow(s) on the valve.


## Wiring instructions

- All wiring must be in accordance with local regulations and national electrical codes and should be carried out by authorised personnel only.
- Make sure that the line power supply is in accordance with the power supply specified on the device.
- See also the instructions in paragraph "Application".


## ! WARNING

## Shock Hazard

Disconnect the power supply before wiring connections are made to prevent personal injury.

## Equipment Damage Hazard

Make and check all wiring connections before applying power to the system. Short circuited or improperly connected wires may result in permanent damage to the unit.

## Wiring diagrams

## 3-point models

FA-3300


FA-3303 / -3305


FA-330x-7411: $230 \mathrm{~V} \sim \stackrel{( }{\bar{\sigma}}$
FA-330x-7416: 24 V~

Proportional models
FA-3341


## Adjustments

## WARNING

## Shock Hazard

Great care must be taken when the cover is removed (by authorised personnel only) for adjustment or inspection.

In all other cases when the cover is removed the power must be switched off.

Do not touch or attempt to connect or disconnect wires when the electrical power is on.

Actuators with $0 . . .10 \mathrm{~V}$ or $0 . . .20 \mathrm{~mA}$ positioner (example below with $0 . . .10 \mathrm{~V}$ )


## Selecting positioner action:

The action can be selected by disconnecting plug "ST1", turning it 180 degrees and reconnecting it, as in the following illustration:


## Slope adjustment:

## - Direct Action:

At the maximum input signal, adjust the 0\% position with "potentiometer A".
At the minimum input signal, adjust the $100 \%$ position with "potentiometer B".

2... 10 V Maximum input signal Adjust with "pot.A".
0... 8 V Minimum input signal

Adjust with "pot.B".

## - Reverse Action

At the minimum input signal, adjust the 0\% position with "potentiometer A".
At the maximum input signal, adjust the $100 \%$ position with "potentiometer B".


## Note:

The maximum input signal must always exceed the minimum input signal by at least 2 Volts.

## Applications

Parallel and sequenced operation of actuators

## A caution

Parallel connection is only possible using isolation relays. If the parallel running motors do not have separately switched power supplies one or more motors will start to cycle at the end of travel.

## Actuators with built-in positioner for controllers with $0 . . .10 \mathrm{~V}$ output



The controller output $0 \ldots 10 \mathrm{~V}$ can operate several actuators with electronic positioner for $0 . .10 \mathrm{~V}$ or $0 . . .20 \mathrm{~mA}$ control. The electrical wiring for parallel and sequenced operation is identical. The sequencing and action of the actuator can be adjusted individually on each positioner. Each positioner has its own adjustment for starting point between $0 . . .8 \mathrm{~V}$ and end point between $2 \ldots 10 \mathrm{~V}$. Using the minimum adjustable span of $20 \%$ therefore enables a maximum of 5 sequenced devices. Further sequencing can be accomplished by using additional controller outputs. Each positioner can be set for direct or reverse action.
Adjustments for Y1, Y2 and Y3 (example)


## Reversible actuator without positioner for floating controller.

Sequencing two actuators without positioner using end switches.


## Parallel operation of actuators without positioner with synchronous motor, condenser and end switches:

Although synchronous motors have the same running speed, deviation in travel between motors can accumulate because of varying load during start-stop operation. This deviation depends on the number of on/off cycles and is about $0,5 \%$ per 100 cycles. Periodically switching the actuators to end of travel (e.g. normal position) will improve the synchronous running of the motors.

## Dimensions in mm



## $S$ pecifications

| Actuator models | FA-33xx-741x |
| :---: | :---: |
| Associated valve series and body sizes | - PN16: VG8000 DN 100... 150 <br> - PN25: VBD DN 80... 150 |
| Type of motor Synchronous, Reversible |  |
| Action / Control | - 3-point <br> - 3-point with 5(3) A / 250 VAC auxiliary switches and $2 \mathrm{k} \Omega$ or $135 \Omega$ feedback potentiometer <br> - Proportional with built-in $0 \ldots 10 \mathrm{~V}$ or $0 . . .20 \mathrm{~mA}$ electronic positioner (input impedance $10 \mathrm{k} \Omega$ ) and with 5(3) A / 250 VAC auxiliary switches |
| Hand wheel Standard on all models |  |
| Supply voltage and frequency*) | $\begin{aligned} & 24 \text { VAC + 10\% / -15\%, } 50 \mathrm{~Hz} \\ & 230 \text { VAC + } 10 \% /-15 \%, 50 \mathrm{~Hz} \end{aligned}$ |
| Power consumption | $37 \mathrm{VA}$ |
| (with positioner) | (42 VA) |
| Nominal force $6000 \mathrm{~N}+300 \mathrm{~N}$ |  |
| Nominal stroke 42 mm ; Max. 45 mm |  |
| Nominal running speed $17 \mathrm{~mm} / \mathrm{min}$ |  |
| Enclosure Protection IP 65 |  |
| Materials: |  |
| Stem Stainless steel ( material DIN W-Nr. 1.4305 )Cover Pressed sheet steel (lacquered) |  |
|  |  |
| Operating and Storage $-20 \ldots+60^{\circ} \mathrm{C}$ <br> Conditions R.H. $10 \ldots . .90 \%$, non condensing |  |
|  |  |
| Electrical Connection screw connector $2,5 \mathrm{~mm}^{2}$ |  |
| Cable relief $1 \times$ PG 11 |  |
| Net weight $7,5 \mathrm{~kg}$ |  |
| Approvals | European Directives: <br> EMC ( 89 / 336 / EEC) <br> LVD (73 / 23 / EEC) |

${ }^{*}$ ) For other supply voltage and frequency, please contact your Johnson Controls supplier.

The performance specifications are nominal and conform to acceptable industry standards. For application at conditions beyond these specifications, consult the local Johnson Controls office. Johnson Controls, Inc. shall not be liable for damages resulting from misapplication or misuse of its products.

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