## Product features

## Simple direct mounting

## Manual override

Adjustable angle of rotation
High functional reliability

Home position

Straightforward direct mounting on the Ball Valve with only one screw.
The assembly tool is integrated in the plug-on position indicator. The mounting position in relation to the fitting can be selected in $90^{\circ} \triangleleft$ steps.
Manual override with push button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation with mechanical end stops.
The actuator is overload-proof, requires no limit switches and automatically stops when the end stop is reached.

When the supply voltage is switched on for the first time, i.e. at commissioning or after pressing the gear disengagement switch, the actuator moves to the home positon. Factory setting: Y2 (counter-clockwise rotation)

| Rotary actuator | Rotary valves |
| :---: | :---: |
| $\curvearrowright \mathrm{Y} 2$ | Close |
| $\mathrm{Y} 1 \curvearrowleft$ | Open |

The actuator then moves into the position defined by the control signal.
Mode of operation The actuator is controlled with a standard modulating signal of DC 2(0)...10V and moves to the position defined by the control signal. The measuring voltage $U$ serves for the electrical display of the damper position $0 . . .100 \%$ and as slave control signal for other actuators.

Adaption Automatic adjustment of operating range and measuring signal $U$ to match the mechanical angle of rotation. Manual triggering of the adaption by pressing the Adaption button.

## Wiring diagrams

## LRQU24-SR / NRQU24-SR

## Modulating control

$1 \sim A C 24 V$
$-\quad+\mathrm{DC} 24 \mathrm{~V}$


Override control (frost protection circuit)



LRQU24 / NRQU24
Open/Close control


| Rotary actuator |  | Rotary valve |
| :---: | :---: | :---: |
| Y2 | $\frown$ | Close |

Electrical installation

Cable lengths

## Note:

When several actuators are connected in parallel, the maximum cable length must be divided by the number of actuators


A = Actuator
C = Control unit
L1 $=$ Belimo connecting cable, $1 \mathrm{~m}\left(4 x 0.75 \mathrm{~mm}^{2}\right)$
L2 $=$ Customer cable
Ltot = Maximum cable length

| Cross section <br> L2 2 | Max. cable length <br> Ltot $=L_{1}+\mathrm{L} 2$ |  | Example for DC |
| :---: | :---: | :---: | :---: |
|  | AC | DC |  |
| $0.75 \mathrm{~mm}^{2}$ | $\leq 30 \mathrm{~m}$ | $\leq 5 \mathrm{~m}$ | $1 \mathrm{~m}(\mathrm{~L} 1)+4 \mathrm{~m}(\mathrm{~L} 2)$ |
| $1.00 \mathrm{~mm}^{2}$ | $\leq 40 \mathrm{~m}$ | $\leq 8 \mathrm{~m}$ | $1 \mathrm{~m}(\mathrm{~L} 1)+7 \mathrm{~m}(\mathrm{~L} 2)$ |
| $1.50 \mathrm{~mm}^{2}$ | $\leq 70 \mathrm{~m}$ | $\leq 12 \mathrm{~m}$ | $1 \mathrm{~m}(\mathrm{~L} 1)+11 \mathrm{~m}(\mathrm{~L} 2)$ |
| $2.50 \mathrm{~mm}^{2}$ | $\leq 100 \mathrm{~m}$ | $\leq 20 \mathrm{~m}$ | $1 \mathrm{~m}(\mathrm{~L} 1)+19 \mathrm{~m}(\mathrm{~L} 2)$ |

## Dimensions [mm]



Operating controls and indicators
(1) Direction of rotation switch

Switching over: Direction of rotation changes
(2) Push button and green LED display

Off:
No voltage supply or fault
On: In operation
Press button: Switches on angle of rotation adaptation followed by standard operation
(3) Push button and yellow LED display

Off:
Standard operation
On: Adaptation or synchronising process active
Press button: No function
(4) Gear disengagement switch

Press button:
Gear disengaged, motor stops, manual override possible
Release button: Gear engaged, synchronisation starts, followed by standard operation

Mounting instructions: LRQU.. + DN15... 40 CCV/ NRQU.. + DN50 CCV

m (mbly)


